```
chan getTask(int worker), task[1:PR](int block1, block2);
chan bodies[1:PR](int worker; point pos[*], vel[*]);
chan forces[1:PR](point force[*]);
process Manager {
  declare and initialize local variables;
  for [time = start to finish by DT] {
    initialize the bag of tasks;
    for [i = 1 to numTasks+PR ] {
       receive getTask(worker);
       select next task; use (0, 0) to signal bag is empty;
       send task[worker](block1, block2);
     }
  }
}
process Worker[w = 1 to PR] {
  point p[1:n], v[1:n], f[1:n]; # position, velocity
                            # force and mass for each body
  double m[1:n];
  declare other local variables; initialize all local variables;
  for [time = start to finish by DT] {
    while (true) {
       send getTask(w); receive task[w](block1, block2);
       if (block1 == 0) break; # bag is empty
       calculate forces between bodies in block1 and block2;
     }
    for [i = 1 to PR st i != w]
                                          # exchange forces
       send forces[i](f[*]);
    for [i = 1 \text{ to } PR \text{ st } i != w]
       receive forces[w](tf[*]);
       add values in tf to those in f;
     }
    update \mathbf{p} and \mathbf{v} for my block of bodies;
    for [i = 1 \text{ to } PR \text{ st } i != w]
                                          # exchanges bodies
       send bodies[i](w, p[*], v[*]);
    for [i = 1 \text{ to } PR \text{ st } i != w] 
       receive bodies[w](worker, tp[*], tv[*]);
       move bodies of worker from tp and tv to p and v;
     }
     reinitialize f to zeros;
   }
}
```

```
Figure 11.12 Manager/workers program for the n-body problem.
```

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